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A BAYESIAN EXPLANATION OF AN APPARENT FAILURE RATE  
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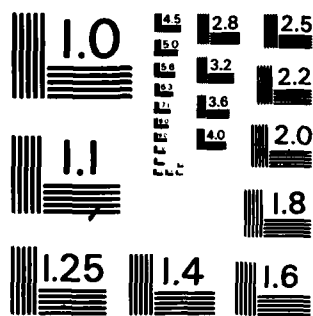
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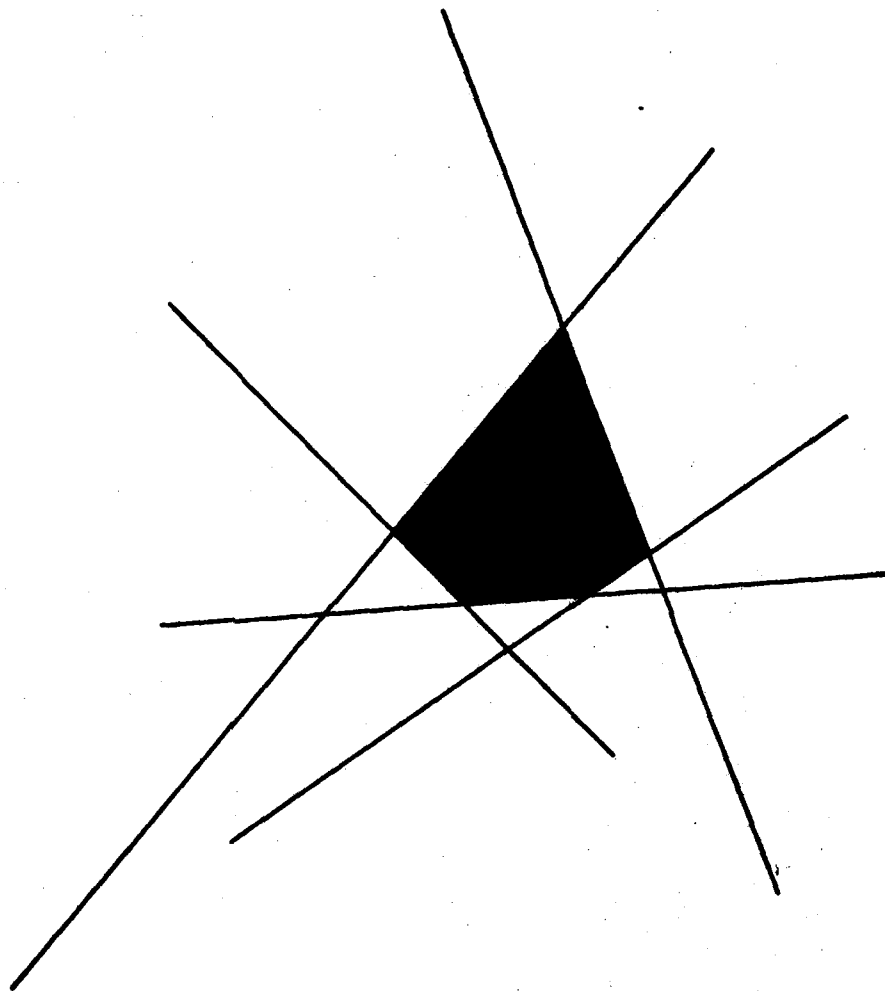
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by  
RICHARD E. BARLOW

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Operations Research Center Research Report No. 83-13

Richard E. Barlow

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U. S. Army Research Office - Research Triangle Park

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#### ACKNOWLEDGEMENT

This apparent paradox was first brought to my attention by Dr. William Vesely, many years ago.

ABSTRACT

*The author*

For the exponential life distribution model and any prior distribution for the failure rate parameter, the predictive distribution has a decreasing failure rate. We give a Bayesian explanation of why this is logically reasonable.

# A BAYESIAN EXPLANATION OF AN APPARENT FAILURE RATE PARADOX

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Richard E. Barlow

For many devices, wear-out does not seem likely--at least not within the time frame of interest. For such devices, an exponential life distribution model may be used; i.e., for random lifetime  $X$ ,

$$P[X > x \mid \lambda] = e^{-\lambda x}.$$

However, information about  $\lambda$  must come from data and/or engineering judgment. In the exponential case and relative to  $\lambda$ , the data can be summarized by  $k$ , the observed number of failures and  $T$ , the observed total time on test. Given  $(k, T)$ , suppose a posterior density is calculated based on a prior  $\pi(\lambda)$ . The predictive survival probability to age  $x$  is then

$$\bar{F}(x \mid k, T) = \int_0^{\infty} P[X > x \mid \lambda] \pi(\lambda \mid k, T) d\lambda. \quad (1)$$

It is well known that for all priors,  $\pi$ , the predictive distribution has a decreasing failure rate function in  $x$  [cf. Theorem 4.7, Page 103, Barlow and Proschan (1981)] when it exists. However, at first glance, this result seems highly unreasonable. If the device does not wear out, why should we predict its future life by a model [the predictive distribution] which actually has a decreasing failure rate?

Denote this predictive failure rate function by  $r(x \mid k, T)$  where, using (1),



$$r(x | k, T) \stackrel{\text{Def}}{=} \frac{\int_0^{\infty} \lambda e^{-\lambda x} \pi(\lambda | k, T) d\lambda}{\int_0^{\infty} e^{-\lambda x} \pi(\lambda | k, T) d\lambda} . \quad (2)$$

Figure 1 illustrates our apparent paradox.

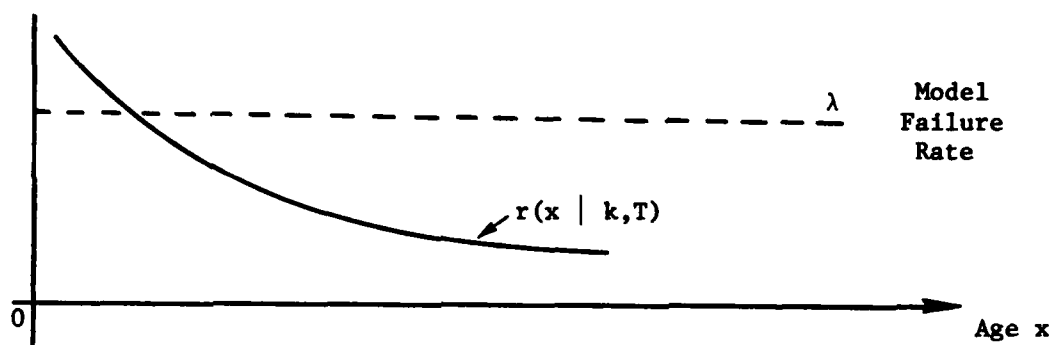


FIGURE 1

COMPARISON OF PREDICTIVE FAILURE  
RATE AND MODEL FAILURE RATE,  $\lambda$

A Bayesian explanation of Figure 1 may be instructive. Note that from (2),

$$r(0 | k, T) = \int_0^{\infty} \lambda \pi(\lambda | k, T) d\lambda = E[\lambda | k, T] \quad (3)$$

so the posterior mean for  $\lambda$  estimates  $r(0 | k, T)$ . Now suppose a new device (exchangeable with our sample devices) were to survive  $x$  hours, then from (2)

$$r(x | k, T) = \frac{\int_0^{\infty} \lambda e^{-\lambda x} \pi(\lambda | k, T) d\lambda}{\int_0^{\infty} e^{-\lambda x} \pi(\lambda | k, T) d\lambda} .$$

But, by Bayes theorem

$$\pi(\lambda | k, T, X > x) = \frac{e^{-\lambda x} \pi(\lambda | k, T)}{\int_0^{\infty} e^{-\lambda x} \pi(\lambda | k, T) d\lambda}$$

so that

$$\begin{aligned} r(x | k, T) &= E[\lambda | k, T, X > x] \\ &= E[\lambda | k, T + x] . \end{aligned} \tag{4}$$

Hence our estimate for  $r(x | k, T)$  based on our updated information, namely that another device has survived time  $x$ , produces an estimate for  $\lambda$  different from  $r(0 | k, T)$ .

It is proved in Barlow and Proschan (1979) that for  $g$  nondecreasing,  $\int_0^{\infty} g(\lambda) \pi(\lambda | k, T) d\lambda$  is decreasing in  $T$ . Expression (3) is the special case  $g(\lambda) = \lambda$  so that  $E[\lambda | k, T] \geq E[\lambda | k, T + x]$  for all priors.

Example:

If  $\pi(\lambda | a, b) = \frac{b^a \lambda^{a-1} e^{-b\lambda}}{\Gamma(a)}$ , the natural conjugate prior, then

$$\bar{F}(x | k, T) = \left( \frac{b + T}{b + T + x} \right)^a$$

and

$$r(x \mid k, T) = \frac{a}{b + T + x}$$

which is obviously decreasing in  $x$ .

Conclusion:

The source of the confusion concerns the difference between a *model* based on prior assumptions, such as constant failure rate, and a *predictive distribution* based on *current* information. We would *not* use the predictive distribution (1) as our model, since we believe in constant failure rate. However, were we asked to predict whether or not a *new* device (exchangeable with the sample devices) would survive to age  $x$ , we would use (1) based on current information.

On the other hand, were we to characterize a new set of say,  $m$ , devices, exchangeable with our sample, we would say that each has an exponential life distribution with expected failure rate  $E[\lambda \mid k, T]$  and  $\pi(\lambda \mid k, T)$  would fully measure our uncertainty about that failure rate. However, were we asked to predict how many will fail in time period  $[0, t]$ , we would use the predictive distribution and calculate

$$mE_{\lambda}[1 - e^{-\lambda t} \mid k, T] = mF(t \mid k, T).$$

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